

Regev's Main Average-Case to Worst-Case Lemma

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We show the main part of Regev's [Reg09] proof that (under certain conditions) it is possible to relate the *average-case* hardness of the learning with errors problem (LWE) to the *worst-case* hardness of bounded distance decoding in a given lattice (BDD).

Preliminaries. We use the following parameters:

n - security parameter.

α - noise parameter ($= \frac{1}{\text{poly}(n)}$).

q - modulus ($\gg \frac{1}{\alpha}$, sometimes even $q = \exp(n)$).

Recall that for a continuous distribution D_r (with standard deviation r), $\tilde{D}_{L,r}$ denotes a discrete distribution over a lattice (or coset of a lattice) L such that every vector $\vec{z} \in L$ has probability mass proportional to $D_r(\vec{z})$.

1 The Main Lemma

In addition to an oracle that solves LWE, the reduction from BDD to LWE also needs access to an oracle that samples short vectors in Λ^* (Regev [Reg09] and Peikert [Pei09] show how to construct such an oracle in specific settings). Additionally it relies on the following properties of the LWE error distribution:

- The LWE error distribution is a projection of a spherical distribution $D_{\alpha q}$ onto its first coordinate.
- The distribution $D_{\alpha q}$ is smooth in the following sense: If Λ is some lattice (or coset of a lattice) with $\lambda_n(\Lambda) \ll \alpha q$ then if we choose $\vec{x} \leftarrow \tilde{D}_{\Lambda,r}$ and $\vec{y} \leftarrow D_s$ such that $r^2 + s^2 = (\alpha q)^2$ then the induced distribution on $\vec{x} + \vec{y}$ is close to $D_{\alpha q}$.

For example the n -dimensional discrete Gaussian has these properties (where $\lambda_n \ll \alpha q$ means $\lambda_n \cdot \omega(\sqrt{\log(n)}) < \alpha q$). In this case the LWE error distribution is just the one-dimensional Gaussian.

Lemma 1 ([Reg09]). *There is an efficient algorithm that takes as input a basis B of an n -dimensional lattice $\Lambda = \Lambda(B)$, another parameter $r \gg \frac{q}{\lambda_1(\Lambda)}$ and a point $\vec{x} \in \mathbb{R}^n$ such that $\text{dist}(\vec{x}, \Lambda) < \frac{\alpha q}{\sqrt{2}r}$ and has access to two oracles:*

- A “global” solver for $\text{LWE}[n, \alpha, q]$ (“global” in the sense that it is unrelated to the input lattice).
- A “lattice specific” sampler from $D_{\Lambda^*,r}$.

The algorithm finds (with overwhelming probability) the (unique) point $\vec{v} \in \Lambda$ closest to \vec{x} .

2 Proof Sketch of Lemma 1

Let $\vec{v} \in \Lambda$ be the closest point to \vec{x} in Λ and let $\vec{t} \in \mathbb{Z}^n$ be the coefficients of \vec{v} when expressed in basis B (i.e., $\vec{v} = B\vec{t}$) and denote $\vec{s} \stackrel{\text{def}}{=} \vec{t} \bmod q$. We show a procedure that uses the sampler for $\tilde{D}_{\Lambda^*,r}$ to generate instances of the distribution $\text{LWE}_{\vec{s}}$. Then, we use the LWE solver to find \vec{s} . (Note

that \vec{s} was not chosen uniformly at random in this case, but we previously showed a random self reduction for LWE from a random \vec{s} to any specific \vec{s} .) Later we show how from \vec{s} one can find \vec{t} thereby solving BDD.

LWE-Generate(B, \vec{x}) (With access to $\tilde{D}_{\Lambda^*, r}$)

1. Draw a sample $\vec{y} \leftarrow \tilde{D}_{\Lambda^*, r}$. Let \vec{a} be the coefficients of \vec{y} in basis B^* (i.e. $\vec{a} = B^T \vec{y}$).
2. Draw an error term $e \leftarrow \Phi_{\frac{\alpha}{2\sqrt{\pi}}}$.
3. Output $(\vec{a}, b = \langle \vec{x}, \vec{y} \rangle + e \bmod q)$.

Claim 1. *The output of LWE-Generate is statistically close to $\text{LWE}_{\vec{s}}$ except that the error parameter is $\beta \leq \alpha$.*

Proof. Need to show:

- (A.) \vec{a} is close to uniform in \mathbb{Z}_q^n .
- (B.) Once \vec{a} is fixed, $\vec{b} = \langle \vec{s}, \vec{a} \rangle + \Phi_{\beta q}$ ($\beta \leq \alpha$).

(A.) Consider the lattice $q \cdot \Lambda^*$ and all its q^n cosets

$$\vec{a}\text{-coset} = \{B^* \vec{a} + q\Lambda^*\} = \{B^* \vec{z} : \vec{z} = \vec{a} \bmod q\}$$

The vector \vec{a} output by the procedure is exactly the coset of \vec{y} . Due to our choice of parameters, all cosets are (almost) equally likely. Indeed, since $r \gg \frac{q}{\lambda_1(\Lambda)} = \frac{q\lambda_n(\Lambda^*)}{n}$ then $\tilde{D}_{\Lambda^*, r}$ is nearly uniform among the cosets.

(B.) Conditioned on any fixed $\vec{a} \in \mathbb{Z}_q^n$, the vector \vec{y} is chosen from the discrete distribution $D_{q\Lambda^* + \vec{a}, r}$ on the \vec{a} -coset. Denoting $\vec{w} \stackrel{\text{def}}{=} \vec{x} - \vec{v}$ we have

$$\begin{aligned} \langle \vec{x}, \vec{y} \rangle &= \langle \vec{v} + \vec{w}, \vec{y} \rangle \\ &= \langle \vec{v}, \vec{y} \rangle + \langle \vec{w}, \vec{y} \rangle \\ &= \langle B\vec{t}, \vec{y} \rangle + \langle \vec{w}, \vec{y} \rangle \\ &= \langle \vec{t}, B^T \vec{y} \rangle + \langle \vec{w}, \vec{y} \rangle \\ &= \langle \vec{s}, \vec{a} \rangle + \langle \vec{w}, \vec{y} \rangle \bmod q \end{aligned}$$

hence $b = \langle \vec{s}, \vec{a} \rangle + \langle \vec{w}, \vec{y} \rangle + e \bmod q$. Notice that \vec{s} , \vec{a} and \vec{w} are fixed and the random part is just \vec{y} and e .

Recall that $\Phi_{\frac{\alpha}{2\sqrt{\pi}}}$ is the projection of $D_{\frac{\alpha}{2\sqrt{\pi}}}$ onto the first coordinate, namely $\langle e_1, D_{\frac{\alpha}{2\sqrt{\pi}}} \rangle$ and since D is spherical then this is also the same as $\langle \vec{u}, D_{\frac{\alpha}{2\sqrt{\pi}}} \rangle$ for any other unit vector \vec{u} . In particular, $\Phi_{\frac{\alpha}{2\sqrt{\pi}}} \equiv \langle \vec{w}, D_{\frac{\alpha}{2\sqrt{\pi}}} \rangle \frac{1}{\|\vec{w}\|} \equiv \langle \vec{w}, D_{\frac{\alpha}{2\sqrt{\pi}\|\vec{w}\|}} \rangle$.

Hence $\langle \vec{w}, \vec{y} \rangle + e \equiv \langle \vec{w}, \vec{y} \rangle + \langle \vec{w}, \vec{z} \rangle = \langle \vec{w}, \vec{y} + \vec{z} \rangle$ where $y \in_R \tilde{D}_{q\Lambda^* + \vec{a}, r}$ and $z \in_R D_s$ where $s = \frac{\alpha}{2\sqrt{\pi}\|\vec{w}\|}$. Now $\|\vec{w}\|$ is “short” so s is “large”. The parameters r, s are chosen large enough so that $\tilde{D}_{q\Lambda^* + \vec{a}, r}$ is close to the continuous D_t where $t = \sqrt{r^2 + s^2}$. Therefore $\langle \vec{w}, \vec{y} \rangle + e \approx \langle \vec{w}, D_t \rangle = \Phi_{\|\vec{w}\| \cdot t}$ and the parameters are such that $\|\vec{w}\| \cdot t \leq \alpha q$. \square

To solve BDD for \vec{x} we can apply the LWE-solver with samples from LWE-Generate to find the vector \vec{s} . However, to solve BDD we need to find \vec{t} (recall $\vec{s} = \vec{t} \bmod q$). To do this, first observe that $\vec{v} = B\vec{t} = B\vec{s} + B(q\vec{z})$ for some $\vec{z} \in \mathbb{Z}^n$ and consider $\vec{x}' = \frac{\vec{x} - B\vec{s}}{q} = \frac{\vec{x} - \vec{v}}{q} + B\vec{z}$. Notice that by this calculation, the vector \vec{x}' is at distance $\frac{\|\vec{w}\|}{q}$ (where $\vec{w} = \vec{x} - \vec{v}$) from the lattice (specifically the point $B\vec{z}$). If we could find the closest lattice point to \vec{x}' we would have \vec{z} and therefore also \vec{v} . To do this just repeat the above argument again and again and at each iteration the distance from the lattice is reduced by a factor of q . After n such iterations we can solve the problem by using, e.g., Babai's nearest plane algorithm.

References

- [Pei09] Chris Peikert. Public-key cryptosystems from the worst-case shortest vector problem: extended abstract. In *41st Annual ACM Symposium on Theory of Computing, STOC 2009*, pages 333–342. ACM, 2009.
- [Reg09] Oded Regev. On lattices, learning with errors, random linear codes, and cryptography. *JACM*, 56(6), 2009.